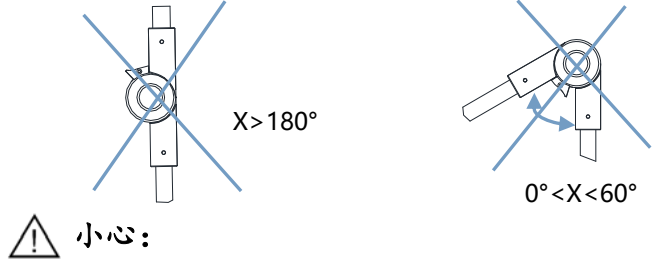
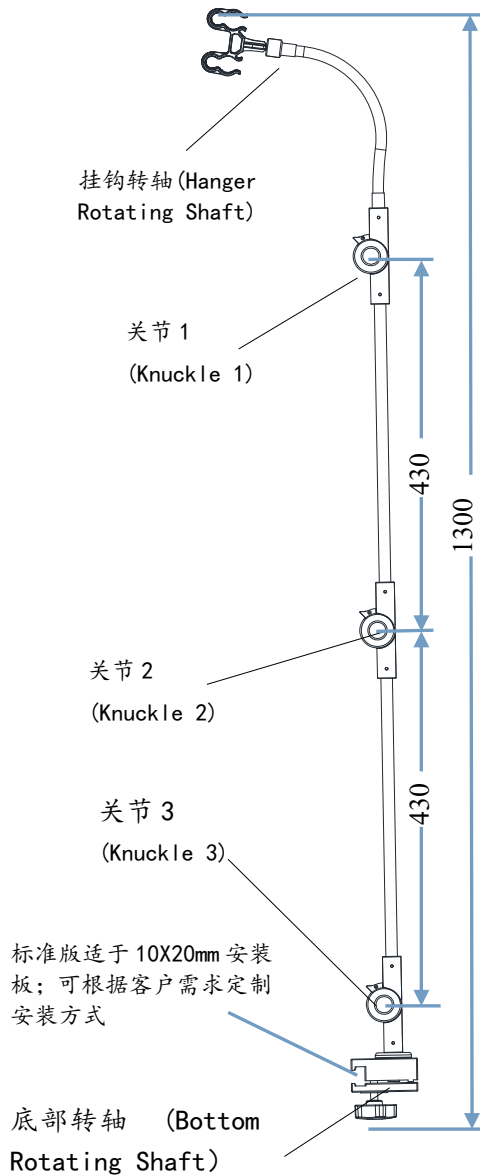


# A916 支撑臂操作说明 (Operation Manual of Arm)

## 1、支撑臂简图 (Medical Arm Diagram) :



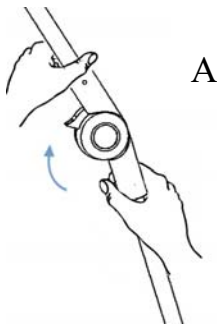
- 所有关节的弯曲角度在 60 到 180 之间, 不能超过这个范围。(Bending angle of all knuckles between 60 to 180 deg, cannot be exceed this range .)
- 由于机械臂关节 1、2、3 内部是单向锁死结构, 按操作指南方式操作, 避免机械臂的损坏。(As the structure of the arm knuckle1、2、3 are unidirectional ratchet structure, according to the manual during operation, to avoid damage occur to the medical arm .)

- 使用前请检查机械臂关节及连接处的安全性, 以免意外伤害患者。(Please check before using the knuckles and joints prior and junctions security, in order to avoid accidental injury to the patient.)

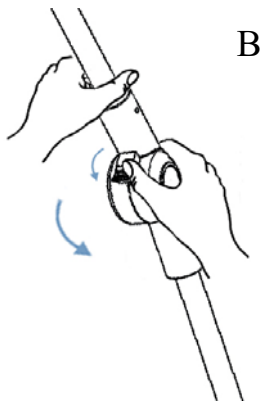
- 操作时注意关节转动的极限位置, 不能强行转动关节超出极限。(Note that the rotation of the knuckles operation limit position, rotating joints can not be forced out of limits.)

本支撑臂最大承重不超过 1Kg。(The support arm palm maximum load 1Kg.)

## 2、关节 1、2、3 操作: (Operation of Knuckle 1、2、3)



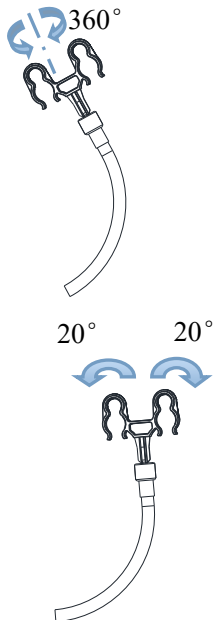
如右图 A, 抬起操作, 直接扳动关节 1、2、3 上下连接杆, 可正向转动关节。(A. Such as the right A, lift operations, pulled directly up and down connecting rod, the knuckle can be rotated to the positive direction.)



B

如图 B: 弯曲操作, 先微微抬起关节前支撑杆, 如 A, 然后一只拨动关节上按钮, 如 B, 另一只手向下压关节前支撑杆, 调至所需角度松开按钮即可。(As shown in Figure B, Bending operation, first slightly lift the anterior rod as A, use one hand to move the pushers of the knuckle as B, one hand pressed anterior strut down to the required angle, release the pushers. )

### 3、塑胶挂钩操作: (Operation of the Plastic Hooks)

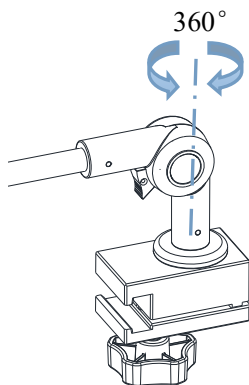


塑胶挂钩可绕轴旋转。(The bigger plastic hook can turn around the shaft.)

小心:

塑胶挂钩侧向弯曲最大 20°。(Plastic hook lateral bending maximum 20°.)

### 4、底部转轴操作: (Operation of the bottom Rotating Shaft)



支撑臂与固定底座之间是阻尼轴连接, 可在 360° 范围内旋转。(The supporting arm is fixed to the bottom plate by damping shaft, can be rotated in the range of 360°.)