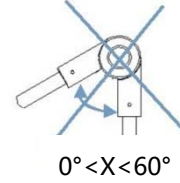
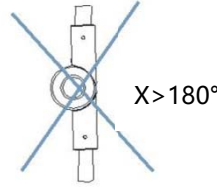
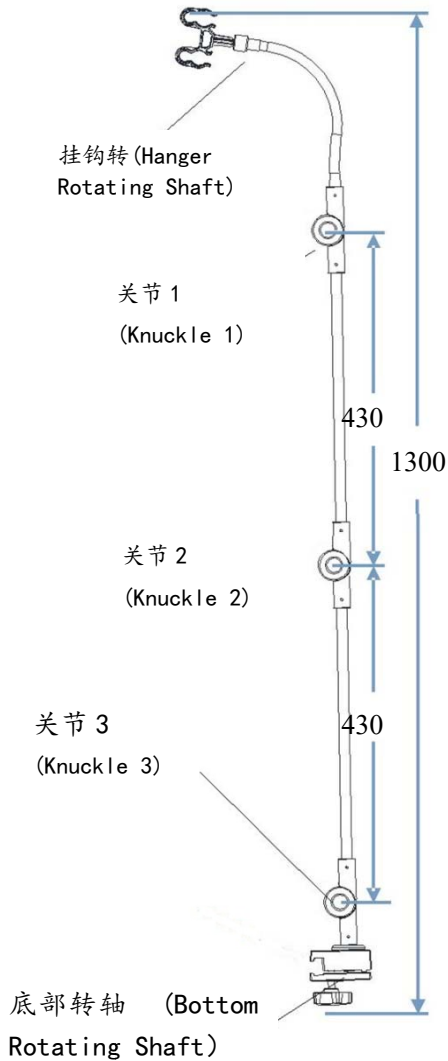


# A911 支撑臂操作指南 (Operation Manual of Arm)

## 1、支撑臂简图 (Medical Arm Diagram) :



⚠ 小心:

- 所有关节的弯曲角度在 60 到 180 之间，不能超过这个范围。(Bending angle of all knuckles between 60 to 180 deg, cannot be exceed this range .)
- 由于机械臂关节内部是阻尼结构，按操作指南方式操作，避免机械臂的损坏。(As the structure of the arm knuckle is damping design, according to the manual during operation, to avoid damage occur to the medical arm, .)

伤害患者。(Please check before using the knuckles and joints prior and junctions security, in order

- to avoid accidental injury to the patient.)
- 操作时注意关节转动的极限位置，不能强行转动关节超出极限。(Note that the rotation of the knuckles operation limit position, rotating joints can not be forced out of limits.)

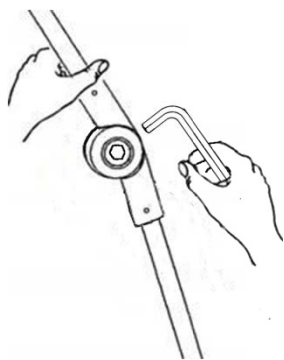
- 本支撑臂最大承重不超过 1.5Kg。(The support arm palm maximum load 1.5Kg.)

## 2、关节操作: (Operation of Knuckle)



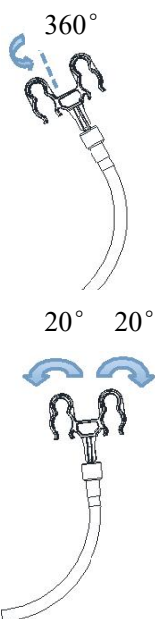
关节为阻尼结构，抬起和弯曲操作，如左图，直接扳动关节上下连接杆，可正向、反向转动关节。( Damping structure, lifting and bending operation as shown in left diagram, pulled straight up and down joint connecting rod, can be forward and reverse rotation of the knuckle .)

### 3、关节锁紧操作：(Operation of Knuckle 2, 3)

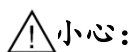


扳手的作用是锁紧关节，是关节能承载负载而不活动；锁紧扳手的力以负载重物不下垂，手动扳动关节方便省力即可。扳手是附件，挂在支臂底部，使用时取出，使用完毕放回即可。(The function of the spanner is to lock the joint, and the joint can bear the load without moving; the force of the wrench is locked, the load is not depressed, and the knuckle is pulled by hand, and the utility model is convenient and labor-saving. The wrench is an accessory. It is hung at the bottom of the support arm. It can be taken out when used and put back after use.)

### 4、塑胶挂钩操作：(Operation of the Plastic Hooks)

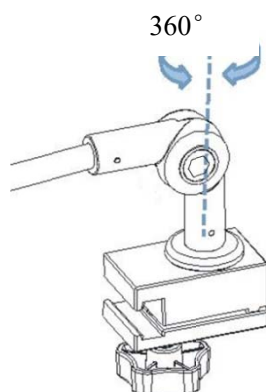


塑胶挂钩可绕轴旋转。(The bigger plastic hook can turn around the shaft.)



⚠️ 小心：  
塑胶挂钩侧向弯曲最大 20°。(Plastic hook lateral bending maximum 20°.)

### 5、底部转轴操作：(Operation of the bottom Rotating Shaft)



支撑臂与固定底座之间是阻尼轴连接，可在 360° 范围内旋转。(The supporting arm is fixed to the bottom plate by damping shaft, can be rotated in the range of 360°.)